**Pulse Oximeter for Low SpO2 Level Detection Using Discrete Time Signal Processing Algorithm**

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**ABSTRACT**

*Oximeter is an important clinical device used for measuring peripheral capillary oxygen saturation (SpO2) in blood and hence accurate results are needed in order to help physicians predict clinical problems in the initial stage(s) of liver or kidney diagnosis. Different issues associate with the accuracy of SpO2 and heart rate measurement accuracy are studied in this work. With the understanding of these issues, a new SpO2 monitoring system is proposed that comprises of a better detection method, novel discrete time signal processing algorithm and a custom-made oximeter probe head. The proposed SpO2 measurement system is capable of determining low levels of SpO2 present in human blood and produce the results in a short time that enable real time monitoring of a patient SpO2. It can also distinguish low level of SpO2 against background noise.*

**INTRODUCTION**

Oxygen is an important element for human body functions such as metabolisms, respirations and immunity etc. Many clinical diseases are caused by the lack of sufficient oxygen supply, which will affect the normal metabolism of cells [1]. Operation rooms (OR) and intensive care units (ICU) require a continuous oxygen concentration monitoring system, and real-time monitoring of oxygen concentration in blood is an important health check item.

Since 1986, pulse oximeters have been the standard of care for monitoring the oxygen concentration of blood to ensure health and safety of patients [2]. Through the use of a pulse oximeter during an operation, the anesthesiologist ensures that oxygen is sufficiently delivered to the tissue during mechanical ventilation [3]. After the successful deployment of the pulse oximeter in the Operating Room (OR) and Intensive Care Unit (ICU), it is currently being widely used in other hospital units and patient clinics as well. Medical professionals believe that arterial SpO2 measured by pulse oximetry, will be the fifth vital sign for human [4], as we previously reported the clinical potential for monitoring hemodynamic changes of the acute scrotum [5].

**Here** SpO2 is the ratio of oxyhemoglobin in the red blood cells to total hemoglobin, representing the body's ability to carry oxygen. Currently, there are two methods for measuring SpO2. The first method is to draw blood from arteries and then use a blood gas analyzer [6] to perform electrochemical analysis [7] for the determination of the partial Pressure of Oxygen (PO2) which is then converted to the peripheral capillary oxygen saturation (SpO2).

Although blood gas analyzer can determine the exact value of oxygen level in the blood, it uses invasive needles to draw the blood from arteries, and thus it cannot perform continuous monitoring of blood oxygen level. Also, it is time-consuming. Furthermore, the cost is high and requires a trained medical professional to perform the test, and hence it can only be performed in the hospitals.

In the second method, sensor is placed on the point/area of intent and two light signals with different wavelengths are produced using a pair of Light Emitting Diodes (LEDs). These signals pass through the blood vessels of human tissue simultaneously, and the detectors receive the reflected signals from the blood. The ratio of the intensities of the two reflected signals with different wavelengths are then calculated and converted to SpO2 via a lookup table [8] based on the Beer-Lambert law [9].

While there are many such commercial oximeters available, their limitations can be summarized in Table 1 with their respective reported solutions. All these limitations produce errors in determining the accurate level of SpO2 which can be overcome by the reported solutions. However, among them, there are two limitations which remain unnoticed, namely the light scattering property of LED and measurement of low SpO2 level.

Available oximeters in the market commonly use LEDs for detection of SpO2, Due to light scattering effects in LED, signal loss or decrease in the signal to noise ratio (SNR) occurs that causes inaccuracy in the measured SpO2. Detection of low SpO2 (< 94%) depends on the low-intensity reflected pulse signals, thus its error can be high, and its measurement time is also very long in order to gather sufficient signal information using pulse oximeter. On the other hand, detection of low SpO2 level is crucial since it indicates abnormal situation in our body.

In this work, a new methodology is developed to address the two aforementioned un-resolved limitations of oximeters. The proposed methodology is described in the following section.

**OXIMETER DESIGN METHODOLOGY**

The design and development of oximeter in this work can be divided into two paths, namely hardware and software design.

Hardware design includes the designing of oximeter sensor head for transmission of signals. The reflected signals are captured using detectors and the corresponding analog signals are converted to discrete signals for further computation using Arduino pro mini driver circuit. These discrete signals are first filtered using our developed algorithm on MATLAB platform, followed by the computations of SpO2 and pulse rate. Graphical User Interface (G.U.I.) is designed in the software design path to show the measured SpO2 level and heart rate. Fig. 1 shows the flow of the oximeter system that is developed in this work.

1. ***Hardware Design***

The hardware module can be divided into sensor and circuit modules as shown in Fig. 2. The sensor module is a custom-made oximeter sensor probe head fabricated using 3D printing as shown in Fig. 3(a), and it consists of Red (R) and Infrared (IR) light laser diodes (LD) and two photodiodes (PD) placed at a distance from the LD as computed from the optical reflection path. Laser diodes are used so as to eliminate the issue of light scattering in LEDs. For safety consideration, the laser diodes (LD) are low power and it is pulsing so that maximum laser light intensity incident on human tissues are keep within the acceptable limit (20mW to 40 mW) with limited maximum pulsed current for the LDs [16].

Fig. 3(b) shows the circuit module that consists a microprocessor (Arduino pro mini), analog to digital converter IC (ADS1115/ ADS105) and transistors. Arduino pro mini microprocessor is used for controlling the emissions of IR and R laser diodes, and the photodiodes are to receive the reflected IR and R signals. Conversion of the received analog signals into the discrete signals is done using analog to digital converter (ADC) IC. These converted signals are then sent to the Microprocessor for discrete time signal processing (DTSP).

1. ***Software Design***

Fig. 4 shows the signal processing algorithm for DTSP, and it consists of three principal steps as explained below.

Ideally, the reflected signal should be as shown in Fig. 5(a), where the peak and valley of the waveform is used for the computation of heart beat and SpO2 [12]. In actual case when SpO2 is above 94%, the reflected waveform does resemble the ideal case as shown in Fig 5(b). However, when SpO2 goes below 94%, as in the case where we intentionally depressed the volunteers’ arm 10 minutes at a pressure of 350 mmHg to limit the blood, the expansion and contraction of the blood vessel walls become very small. Since the detection of the SpO2 is based on the expansion and contraction of the blood vessel walls [12], the signal becomes very weak, and the signal to noise ratio is so small that useful signal cannot be extracted as shown in Fig 5(c). Thus, a special signal processing method has to be developed and the first step in the processing of the saved discrete signals is to filter the noise as shown in Fig 5(d).

The setting of the filter is done through Fourier analysis of the signals implemented using the Fast Fourier Transform (FFT) in MATLAB. The noise peaks are found to be prominent after 9 Hz in IRRAW and RRAW signals, as shown in Fig. 6 (a) and (b) respectively.

To filter out these noise peaks, a low pass filter with the cut off frequency of 9 Hz is applied on the received signals, followed by a mathematical function as shown in Fig.7.

Using the filtered and processed IRRAW and RRAW signals, heart rate computation is done by using Eq. (1), where bn is time interval between two peaks as shown in Fig 8(a) . As illustrates in Fig. 8, the detection of peaks and valleys are first done using MATLAB, and the time interval between the consecutive peak and valley is calculated.

The calculation of the SpO2 is done using Eq. (3) [18], with the help of Ros (ratio of ratios) [18]. Ros is a variable calculated by taking the natural logarithm of the ratio of the

valley (RL) to peak (RH) of the red signal, which is further divided by the natural logarithm of the ratio of the valley (IRL) to peak (IRH) of the infrared signal, as shown in Eq. (2) [19].

In Eq. (2), is the extinction coefficient of red light for reduced hemoglobin, is the extinction coefficient of infrared light for reduced hemoglobin, is the extinction coefficient of infrared light for oxyhemoglobin and is the extinction coefficient of red light for oxyhemoglobin. These values are obtained from Fig.9 for the wavelength of the red light (660nm) and infrared (850 nm) LDs used. These wavelengths are measured using Integrated sphere of model LM-ISP 3.4. , are obtained from Oxyhemoglobin curve and , are obtained from Reduced hemoglobin curve. The narrow chromatic spread of the laser diodes also helps in providing more accurate extinction coefficients for the calculation.

**RESULTS AND DISCUSSION**

Arterial Blood Gas (ABG) test [21] is used as reference to measure the accuracy of Oximeters. Oximeter developed in this work as well as a commercial oximeter commonly used in hospital are used for testing. In order to detect SpO2 <94%, the upper arm of the volunteers is pressed for 10 minutes with the pressure of 350 mm Hg, using proximal and distal cuffs to stop the blood flow in the lower arm, as shown in Fig. 10.

The ABG test is performed by taking blood from the ulnar artery [21], under the supervision of a qualified medical doctor at Chang Gung Memorial Hospital (CGMH), Linkou, Taiwan. The comparison of the test results is shown in Table 2.

ABG test takes around 20 minutes and the process is tedious, Our Oximeter took only 35 seconds with the error rate of ± 2% for SpO2 > 94% and ± 4% for SpO2 < 94%. On the other hand, the commercial oximeter can measure SpO2 > 94% with the error rate of ± 3% within 5-25 seconds but it cannot detect anything for SpO2 < 94%, even after measuring the SpO2 for 3 minutes.

The short measurement time to obtain SpO2 also enable real time monitoring of blood oxygen level. In fact, we do see the time progressing of the SpO2 decrement when the volunteers’ arms were depressed as shown in Fig. 11. The rate of decrease SpO2 might be a useful data for physicians in detecting the blood vessel elasticity, and this is beyond the scope of this work.

While it is good that the oximeter developed can measure low SpO2 when the signal level is low, it is equally important to ensure that the signal that we obtain is indeed useful signal instead of noise. In our measurement, we observed that when our oximeter is measuring the correct SpO2, the IRRAW and RRAW signals have similar patterns as shown in Fig. 12(a) and (b) when upper arms of the volunteers were not depressed and Fig. 12(c) and (d) when upper arms of the volunteers were depressed using proximal and distal cuffs. However, when there is no object or when there is error during measurement as shown by the inconsistent results between the SpO2 and ABG test, the IRRAW and RRAW signals do not have similar patterns as observed in Fig. 12(e) and (f). With this self-detection capability built in, one can further ensure the accuracy of the SpO2.

**CONCLUSION**

In this work, pulse oximeter is designed and developed that is more resilient against light scattering due to the usage of laser diodes, and it can also determine low SpO2level by using signal processing algorithm. This algorithm also enables oximeter to detect measurement error or error due to null object.

Performance of the developed Oximeter was compared with a commercial oximeter using Arterial Blood Gas test as reference. It is experimentally demonstrated that developed Oximeter can measure the SpO2 with the range of 60% to 100% with the minimum error of ± 2% for SpO2 > 94% and ± 4% for SpO2 < 94%, whilst the commercial oximeter cannot provide any reading when the SpO2 <94%.

**ACKNOWLEDGMENT**

We acknowledge the support of the Chang Gung Memorial Hospital, (Taiwan) and Center for Reliability Sciences & Technologies, Chang Gung University (Taiwan). We would like to thank, Vivek Sangwan, Dipesh Kapoor and Udit Narula from Center for Reliability Sciences & Technologies, Chang Gung University (Taiwan) for their technical inputs and insights.

**FUNDING**

This research was supported in by the Chang Gung Memorial Hospital, Linkou, Taiwan, grant: CMRPG3F0641.

**NOMENCLATURE**

*Ros* Ratio of the ratios

*IRH*  Peak of the IR signal.

*IRL*  Valley of the IR signal.

*RH* Peak of the Red signal.

*RL* Valley of the Red signal.

*FFT*  Fast Fourier Transform.

*bpm*  Beats per minute.

*IR*  Infrared light.

*R* Red light.

IRRAW Raw signal from IR sensor.

RRAW Raw signal from R sensor.

CGMH Chang Gung Medical Hospital.

SpO2 Peripheral capillary oxygen saturation.

Extinction coefficient of red light for oxyhemoglobin.

Extinction coefficient of infrared light for oxyhemoglobin.

Extinction coefficient of red light for reduced hemoglobin.

Extinction coefficient of infrared light for reduced hemoglobin.

*bn* Time interval between two peaks.

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**EQUATIONS**

|  |  |
| --- | --- |
|  | (1) |

|  |  |
| --- | --- |
|  | (2) |
|  | (3) |

**Figure Captions List**

|  |  |
| --- | --- |
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Discrete - time signal processing algorithm, SpO2 and Pulse rate computations are performed on received discrete signals.

Designing of oximeter sensor head.

GUI shows SpO2 and Pulse rate

IR and R signals received from Oximeter sensor head

Conversion of analog signals to discrete signals and send them to personal computer.

Hardware Design

(Oximeter sensor head, Arduino mini and ADC circuit)

Software Design (MATLAB)

Arduino circuit

Fig. 1. Research methodology flow chart.

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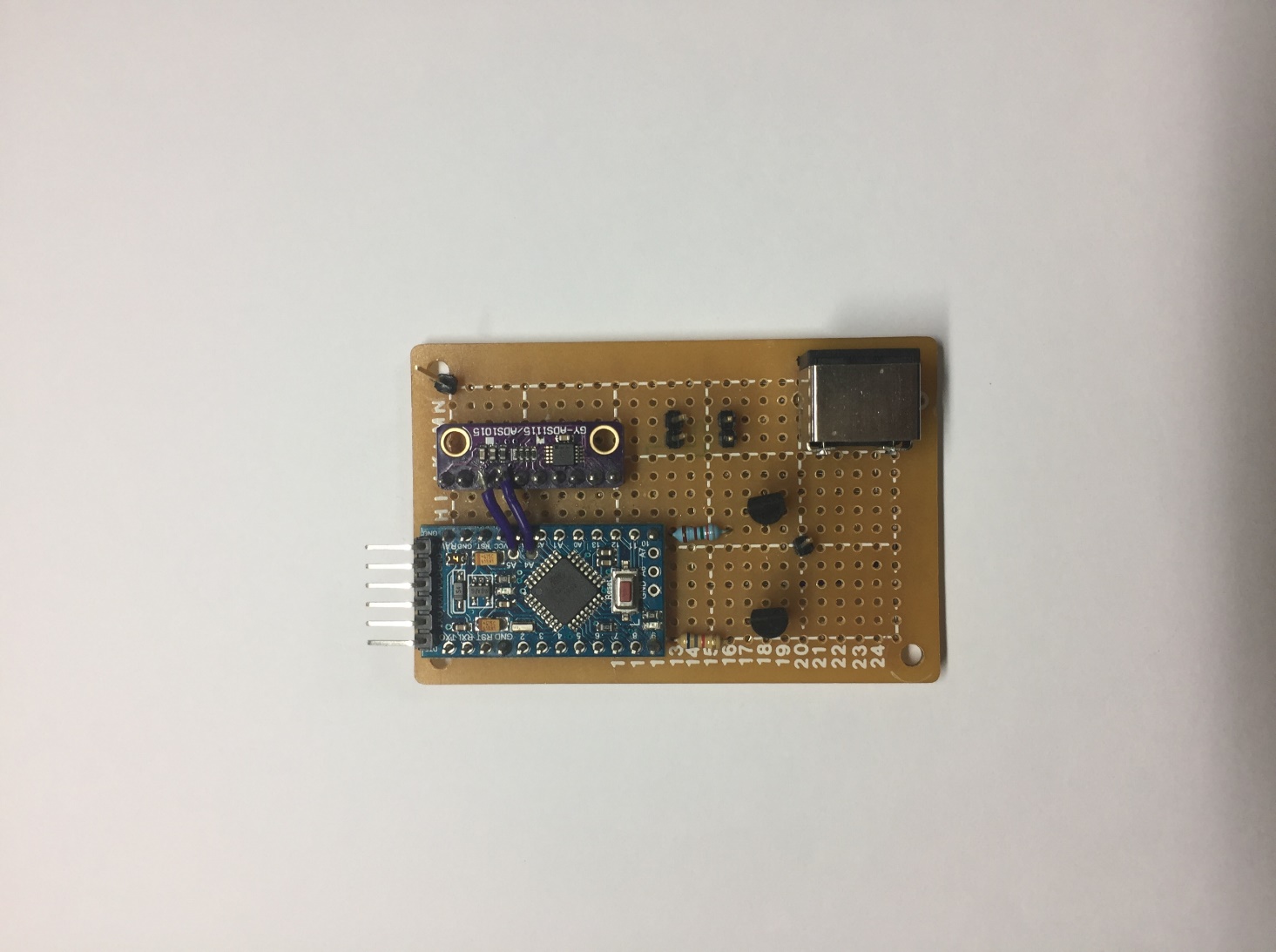
Fig.2 Hardware architecture of oximeter.



Photodiodes

IR laser

R laser



(a)

(b)

Fig. 3 (a). Oximeter sensor’s probe head, (b). Arduino driven circuit for SpO2 measurement

Signal detection and collection.

GUI

Pulse rate calculation

SpO2 (Oxygen concentration in blood) calculation

Patented Signal Processing method

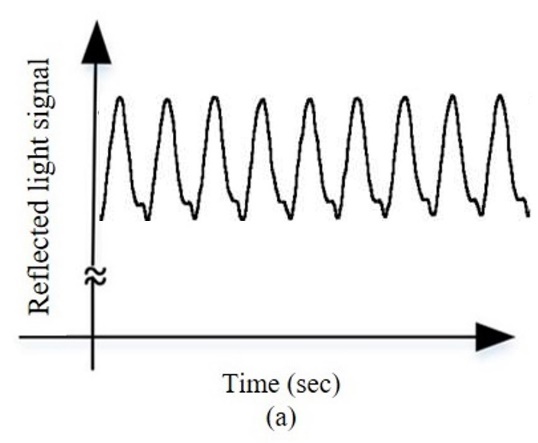
Save the data in .text file

Low pass filter is applied on IRRAW and RRAW

Input data from sensor.

Discrete-time signal processing.

Fig. 4 Signal Processing Algorithm for calculating SpO2, using raw reflected signal from Infrared Laser diode (IRRAW) and Red Laser diode (RRAW).





(b)



(d)



(c)

Fig. 5. (a). Ideal reflected from arteries [17], (b). Reflected IRRAW light signals during experiment without depressing the volunteers’ arms, (c) Reflected IRRAW light signals during experiment with depressing the volunteers’ arms, (d). Filtered signal after applying filter on reflected IRRAW signal.



(b)



(a)

Fig. 6. (a) FFT of the IRRAW signal, (b). FFT of RRAW signal.



Fig. 7. Mathematical function applied on (a) IRRAW vs time (sec) and (b) RRAW vs time (sec)





Fig.8. (a) IRH (peak in IRRAW curve for every second) and IRL (valley in IRRAW curve for every second) detection. The time interval between two peaks (IRH) is bn. (b) RH (peak in RRAW curve for every second) and RL (Valley in RRAW curve for every second) detection.

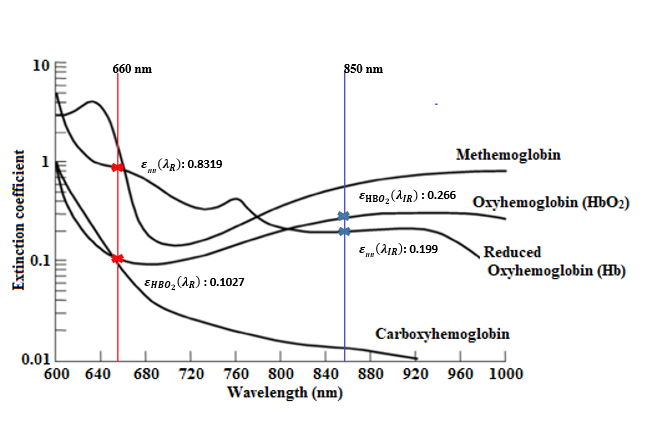


Fig. 9. Extinction coefficients , , and vs. different light wavelength in human blood [17].



Fig.10. Measurement of SpO2,when blood flow is obstructed by the proximal and distal cuffs.



(a)

(b)

Fig.11 Measurement of SpO2 for 10 minutes from the palm of (a). volunteer-1 and (b). volunteer-2



**(a)**

**(b)**

**(c)**

**(d)**

**(e)**

**(f)**

Fig.12 (a) and (b) represent IRRAW and RRAW signals and one can see that they have similar pattern (when blood flow is not obstructed); (c) and (d) represent IRRAW and RRAW signals and again they have similar pattern (when blood flow is obstructed by the proximal and distal cuffs); (e) and (f) IRRAW and RRAW signals have different patterns when there is error during measurement or when there is no object for measurement.

**Table Caption List**

|  |  |
| --- | --- |
| Table 1 | Limitations and their reported solutions for the commercial oximeter |
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TABLE I Limitations and their reported solutions for the commercial oximeter

|  |  |  |
| --- | --- | --- |
| **S/No** | **Limitation and Causes** | **Solution** |
|  | **Motion Artifacts:** Due to the muscles movement during measurement [10]. | Retrospective motion correction technique is employed at the post-process phase using algorithms to eliminate this limitation [11]. |
|  | **Ambient Light:** Interference of the ambience light by the photodiodes during measurement [12]. | A logarithmic amplifier is added in the signal-processing circuitry to subtract the signal components of ambient light or background light from the received signals [13]. |
|  | **Skin Pigmentation:** Presence of dark skin pigmentation [14]. | It can be solved by ‘Munsell color tile system’. In addition, human observation is also required [14]. |
|  | **Abnormal Hemoglobin Molecules:** Detection of the compounds like abnormal hemoglobin or methemoglobin [15]. | It can be eliminated by using a ratio of the first derivative of the first two absorbances of hemoglobin and oxyhemoglobin [15]. |
|  | **Light scattering property of LED:** LED light scattered due to its characteristic of low power and large divergence angle. | Not reported yet. |
|  | **Inability to measure the low SpO2 level:** signal from low SpO2 become very weak and the background noise can be stronger than the signal. | Not reported yet. |

TABLE II Oximeter results and comparison

|  |  |  |  |  |  |  |  |  |
| --- | --- | --- | --- | --- | --- | --- | --- | --- |
| Person | Condition | SpO2%  (ABG) | SpO2 %  (this work) | Error %  (this work) | Measurement Time  (this work) | SpO2 %  (commercial Oximeter) | Measurement Time (commercial Oximeter) | Error %  (commercial Oximeter) |
|  | Before upper arm depressed  (SpO2 > 94%) | 97 | Palm = 97.8 | 0.8 | 35 Seconds | Palm = 100 | 18 seconds | 3 |
| Volunteer 1 | Thumb = 95 | 2 | 35 Seconds | Thumb = 99 | 5 seconds | 2 |
|  | After Upper arm depressed  (SpO2 < 94%) | 66 | Palm = 70 | 4 | 35 Seconds | Palm = no value | 3 minutes | - |
|  | Thumb = 69 | 3 | 35 Seconds | Thumb = no value | 3 minutes | - |
|  | Before upper arm depressing  (SpO2 > 94%) | 98 | Palm = 100 | 2 | 35 Seconds | Palm = 100 | 25 seconds | 2 |
| Volunteer  2 | Thumb = 99 | 1 | 35 Seconds | Thumb = 98 | 15 seconds | 1 |
|  | After Upper arm depressed  (SpO2 < 94%) | Low | Palm = 78 | - | 35 Seconds | Palm = no value | 3 minutes | - |
|  | Thumb = 81 | - | 35 Seconds | Thumb = no value | 3 minutes | - |

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